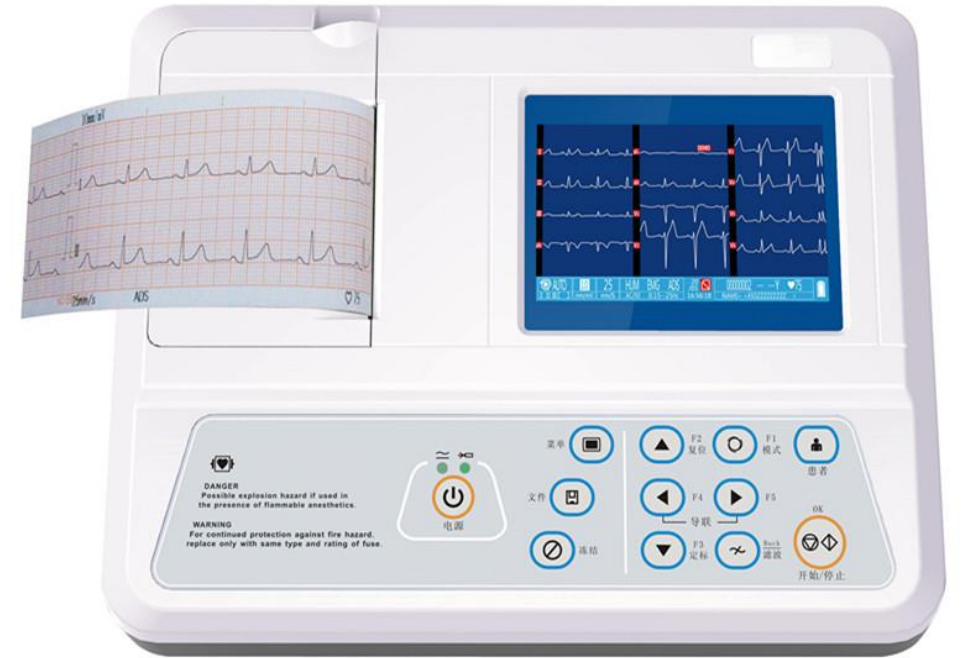
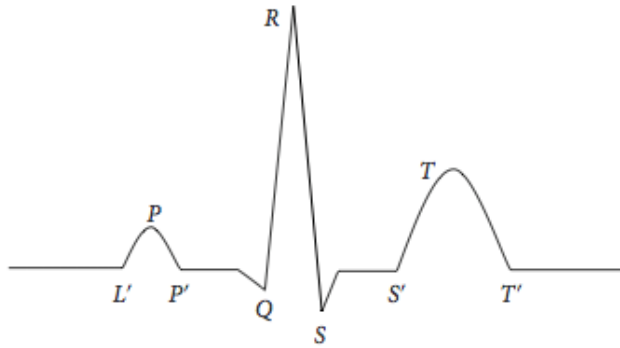


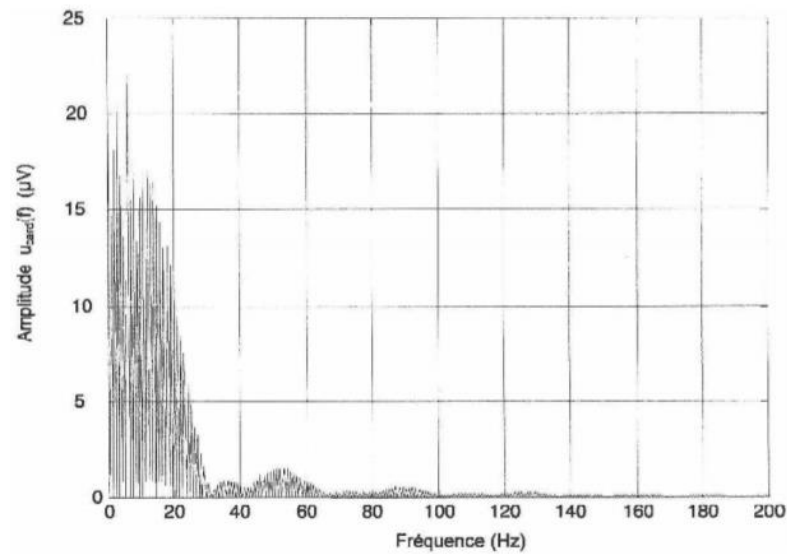
# Atténuation du bruit en électrocardiographie



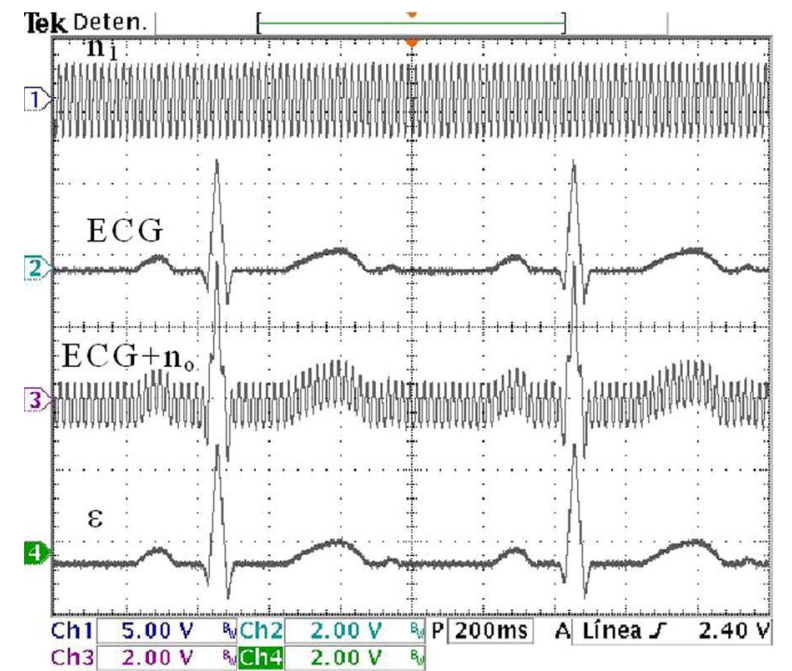
# Problématique:



Composantes d'un  
signal cardiaque



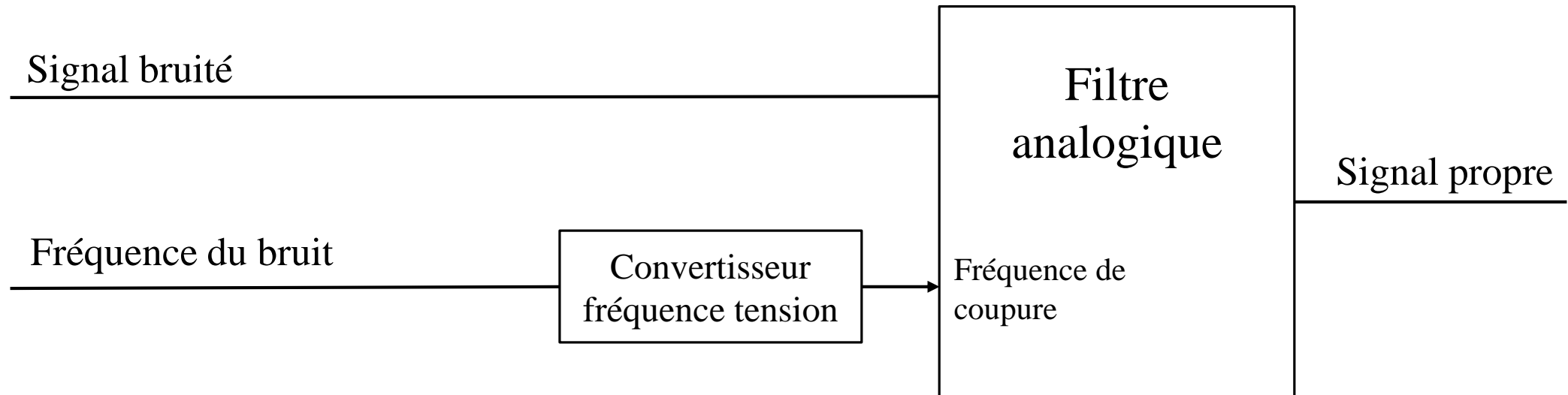
Spectre d'un signal ECG



Atténuation par  
filtrage adaptatif

## Modélisation du système:

---

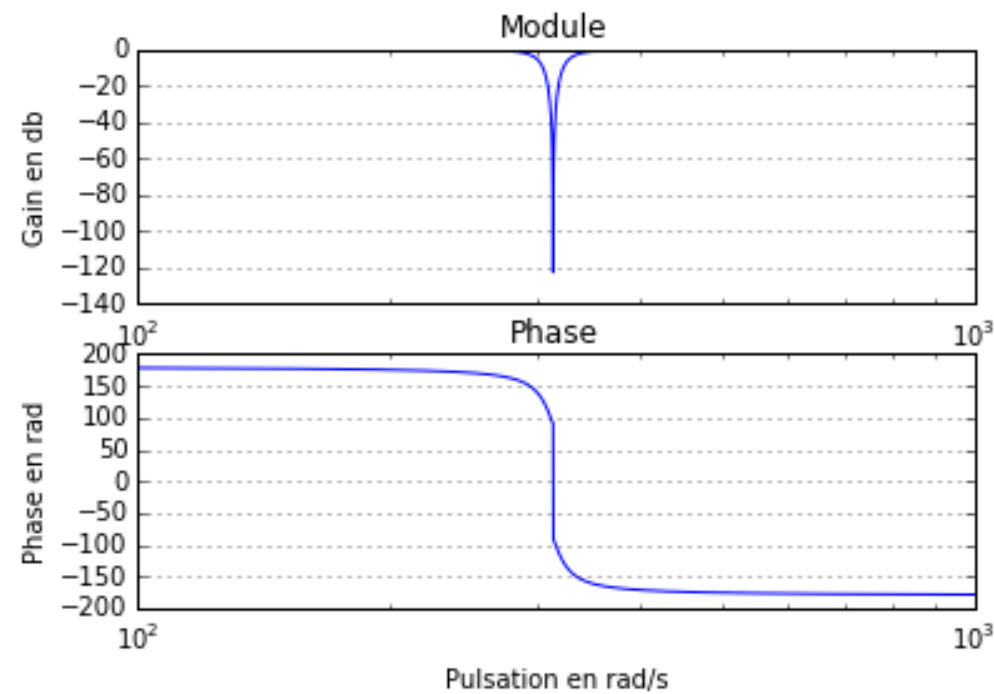
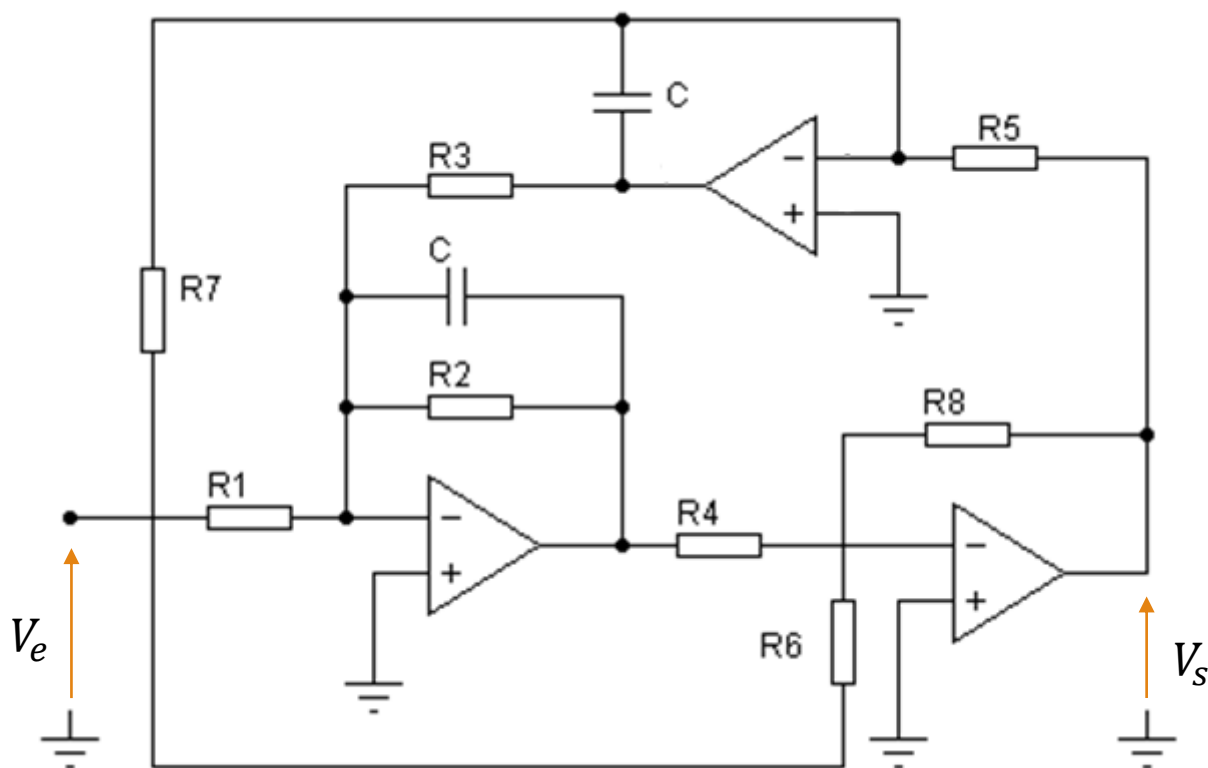


# Sommaire:

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- Filtre utilisé
- Composant variable
- Asservissement en fréquence
- Système final
- Résultats expérimentaux
- Conclusion

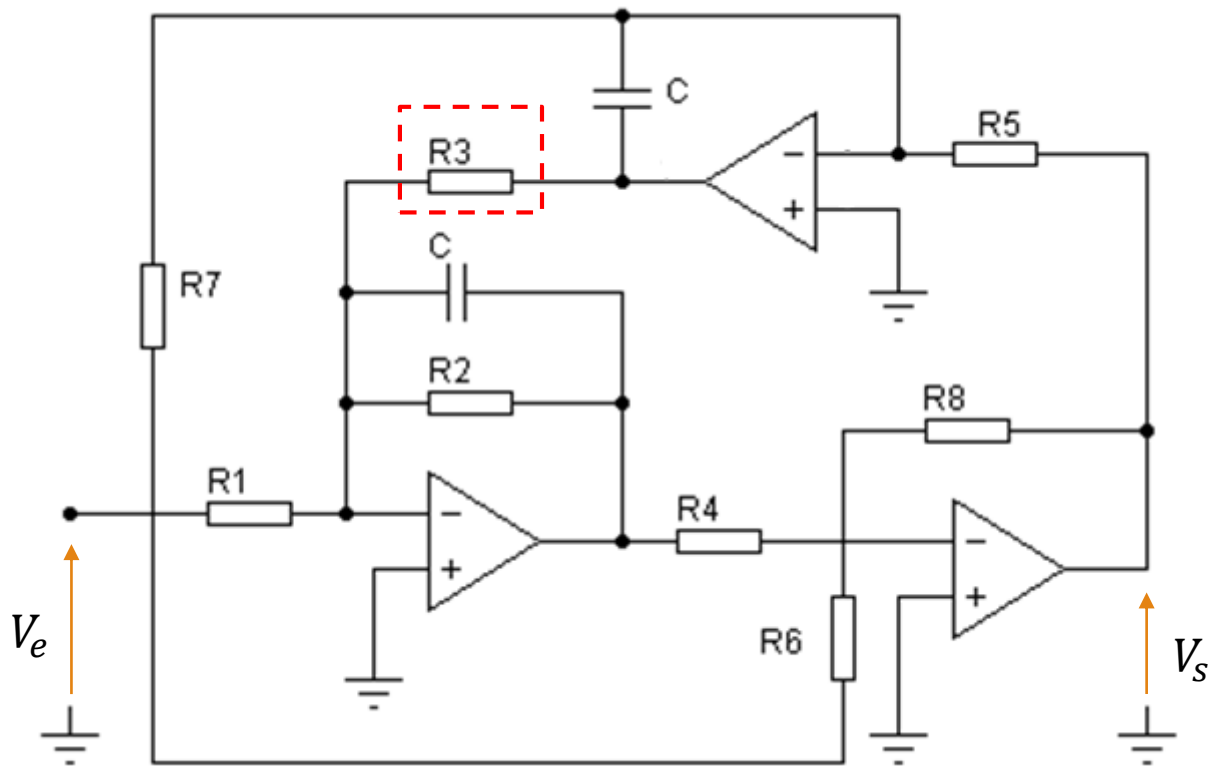
# Filtre coupe-bande 4<sup>ème</sup> ordre: Caractéristiques



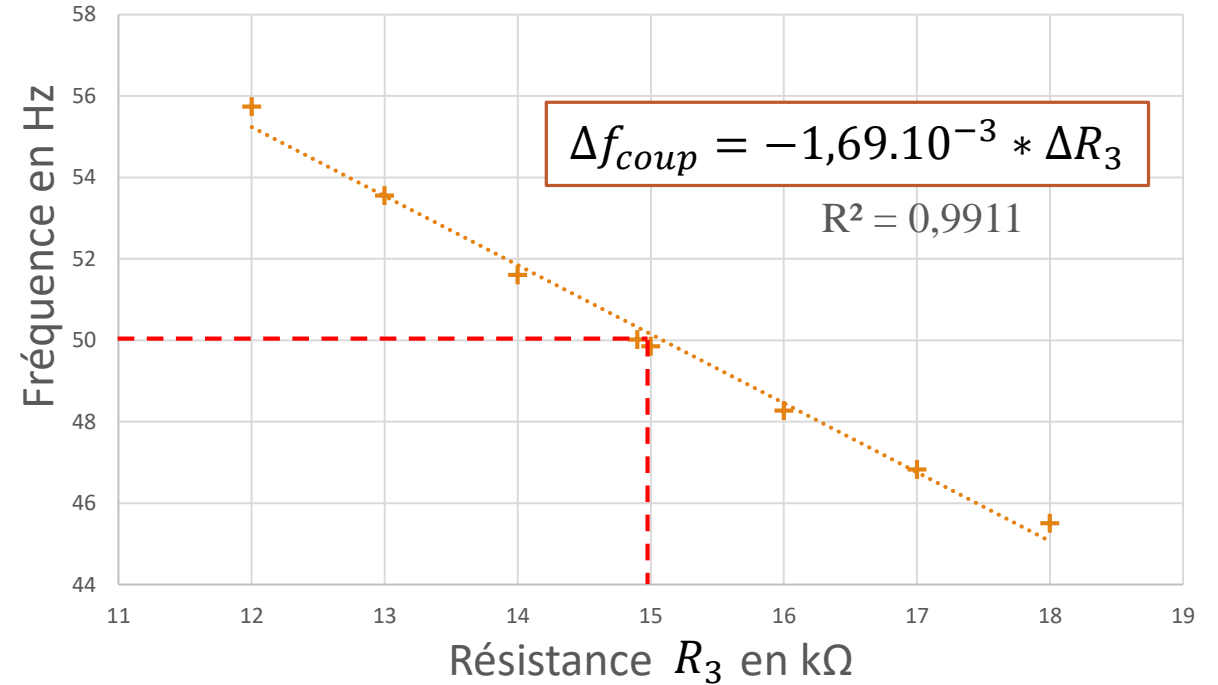
$$Q = 10$$

$$\omega_0 = 2\pi.f = 314,2 \text{ rad/s}$$

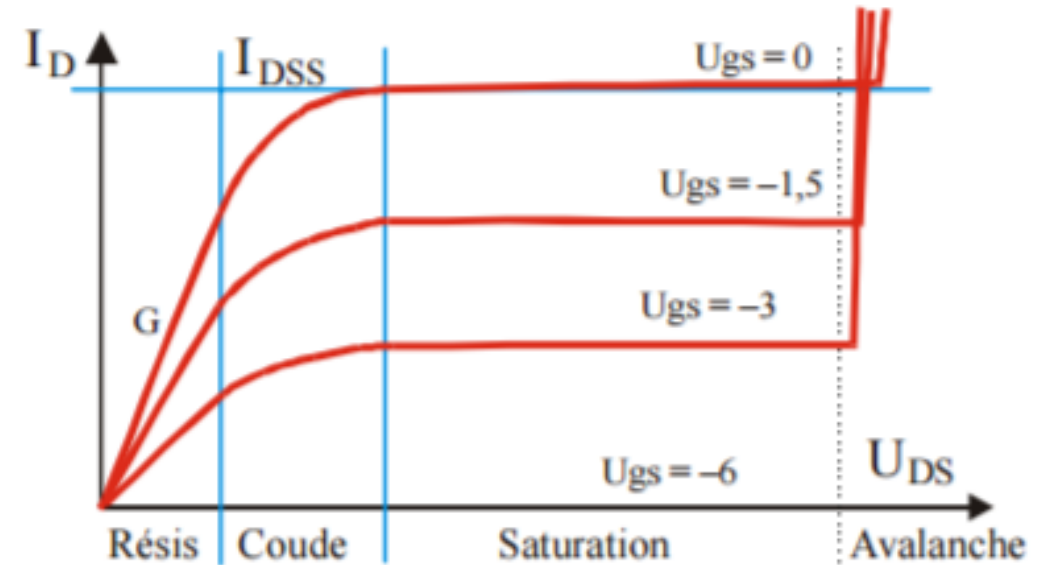
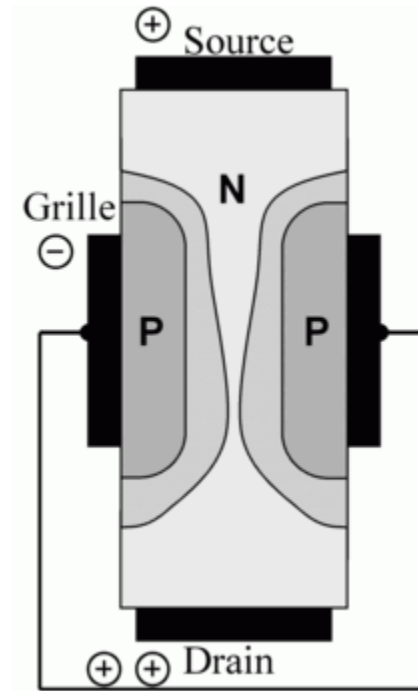
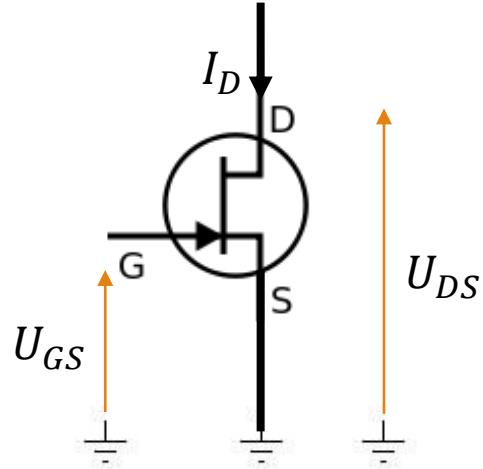
# Filtre coupe-bande 4<sup>ème</sup> ordre: Résistance variable



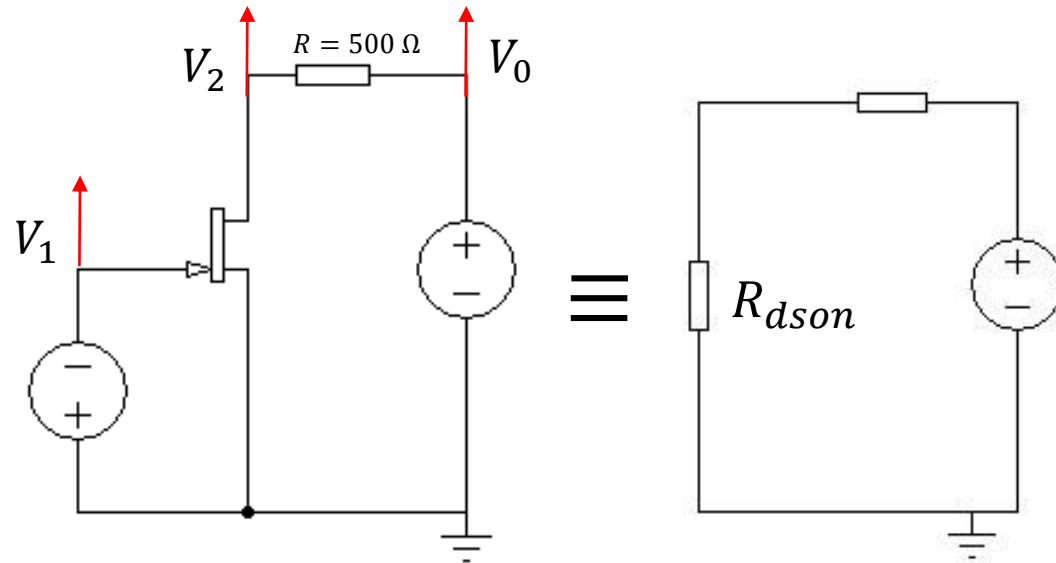
Fréquence de coupure du filtre



# Transistor à effet de champ: Principe de fonctionnement



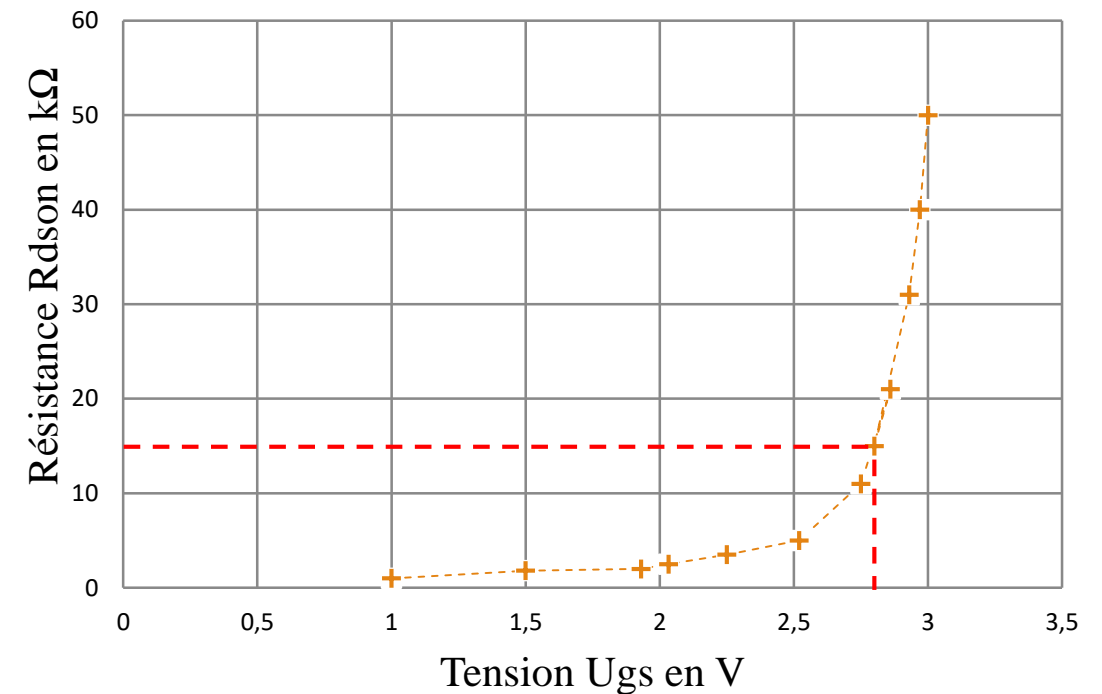
# Transistor à effet de champ: Relevé de la caractéristique



Courant dans le circuit: 
$$I = \frac{V_2 - V_0}{R} = \frac{V_2}{R_{dson}}$$

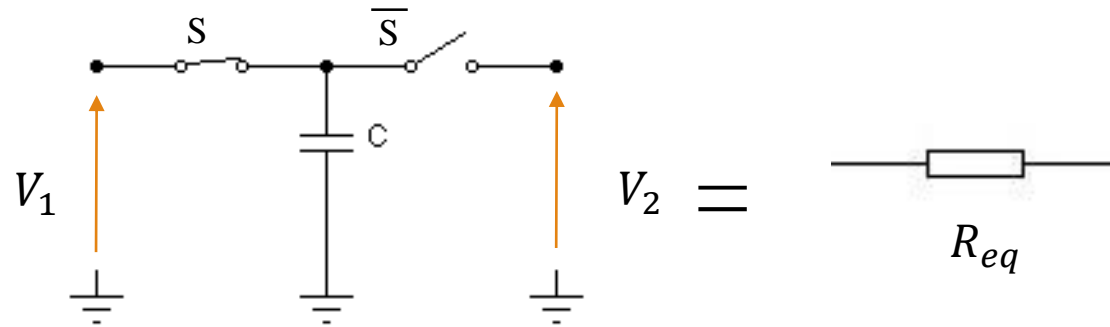
$$R_{dson} = \frac{V_2}{V_2 - V_0} * R$$

Résistance  $R_{dson}$  en fonction de la tension





# Circuit à capacités commutées: Principe de fonctionnement

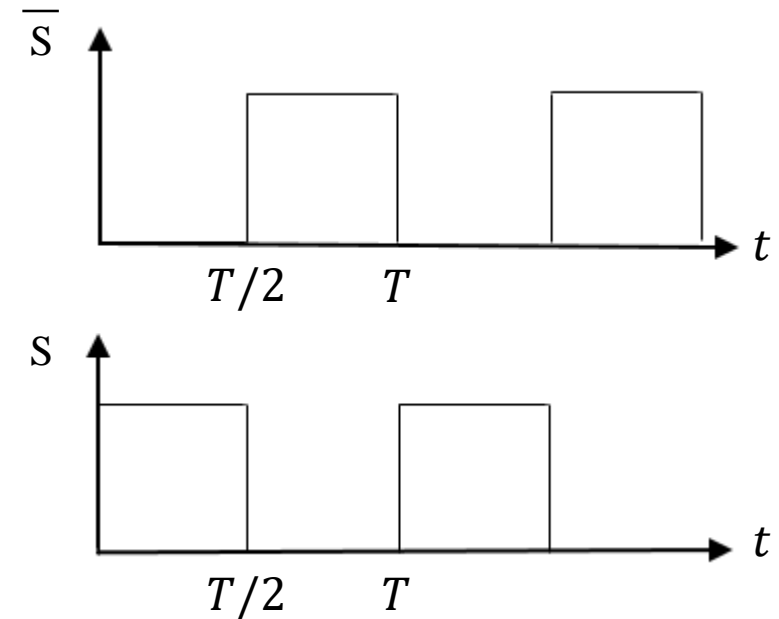


- Pendant  $[0, T/2]$ :  $S$  fermé,  $V_1 = \frac{Q_1}{C}$
- Pendant  $[T/2, T]$ :  $S$  ouvert,  $V_2 = \frac{Q_2}{C}$

$$\Delta Q = Q_2 - Q_1 = C(V_2 - V_1) = C \cdot V_{21}$$

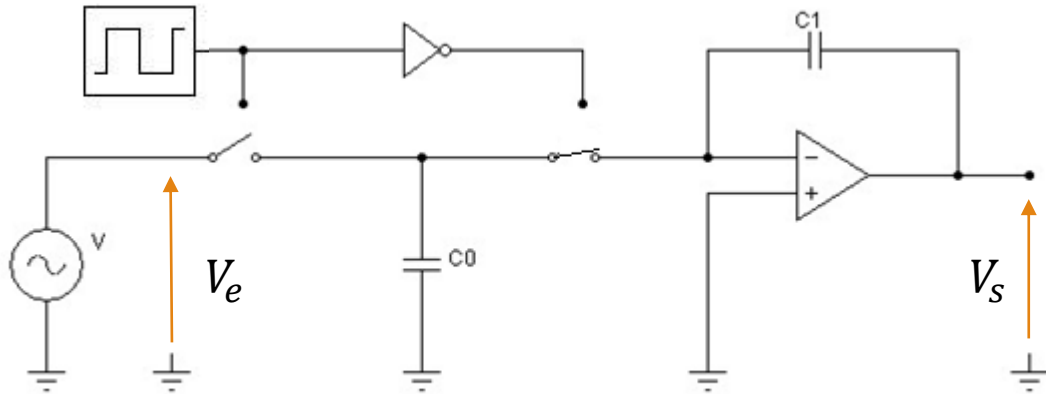
$$I = \frac{\Delta Q}{T} \quad \text{donc} \quad V_{21} = R_{eq} \cdot I \quad \text{avec}$$

$$R_{eq} = \frac{T}{C} = \frac{1}{C \cdot f_{clk}}$$



# Circuit à capacités commutées: Relevé de la caractéristique

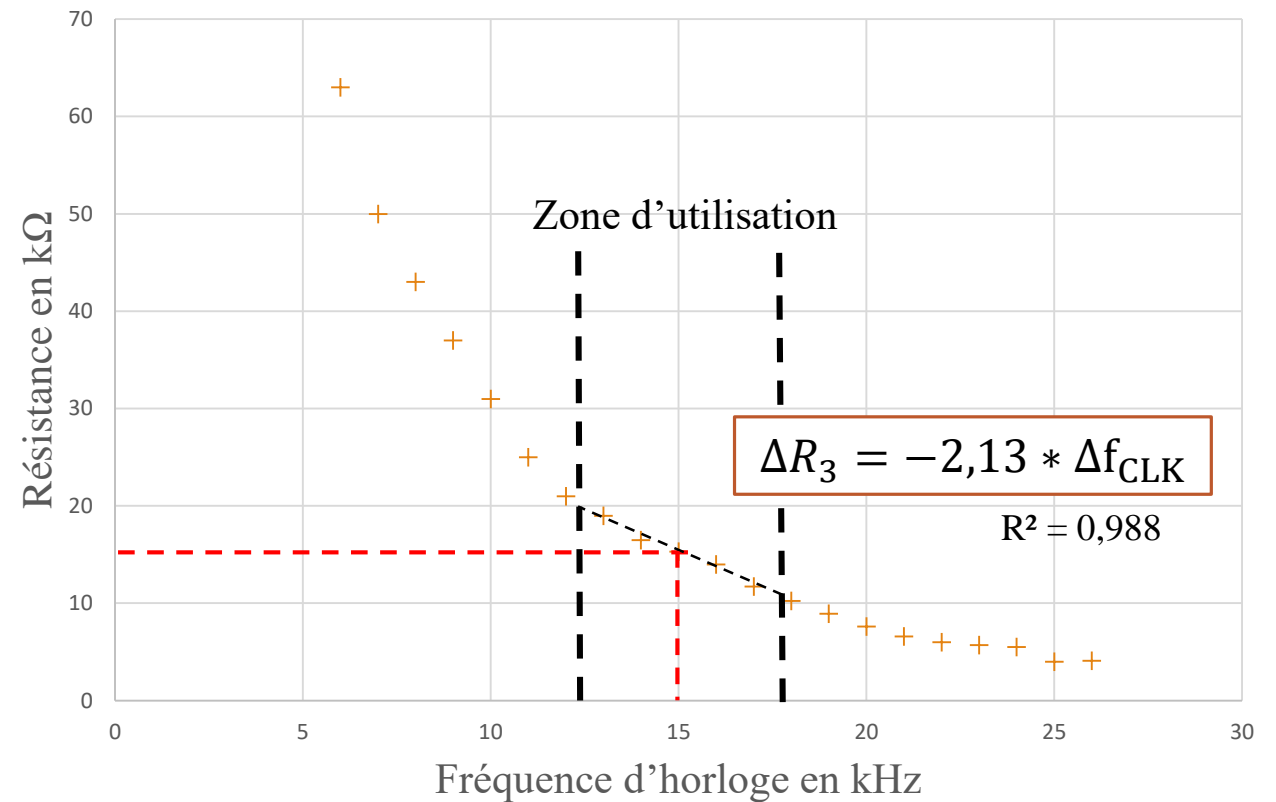
Fréquence d'horloge



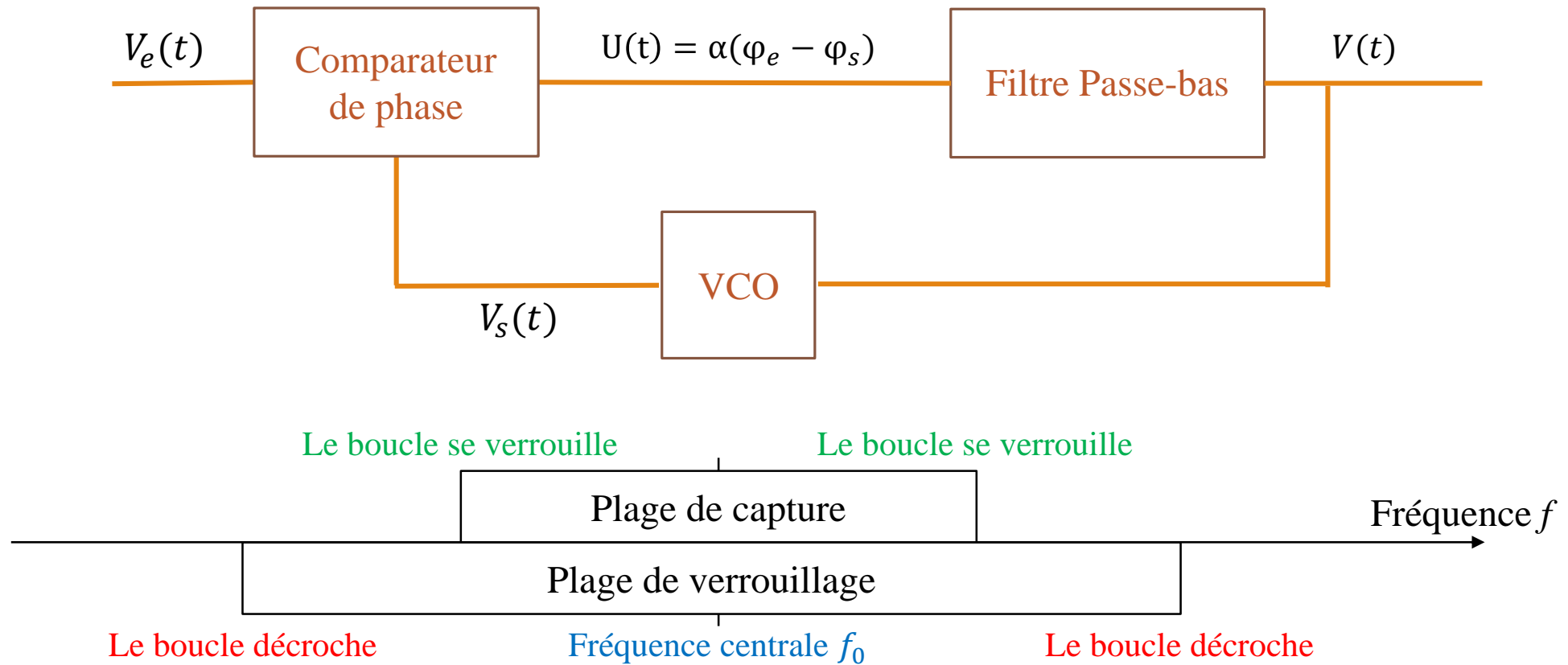
$$H(j\omega) = \frac{V_s}{V_e} = -\frac{1}{jR_{eq}C\omega}$$

$$R_{eq} = \frac{1}{\frac{V_{sl}}{V_{el}} C\omega}$$

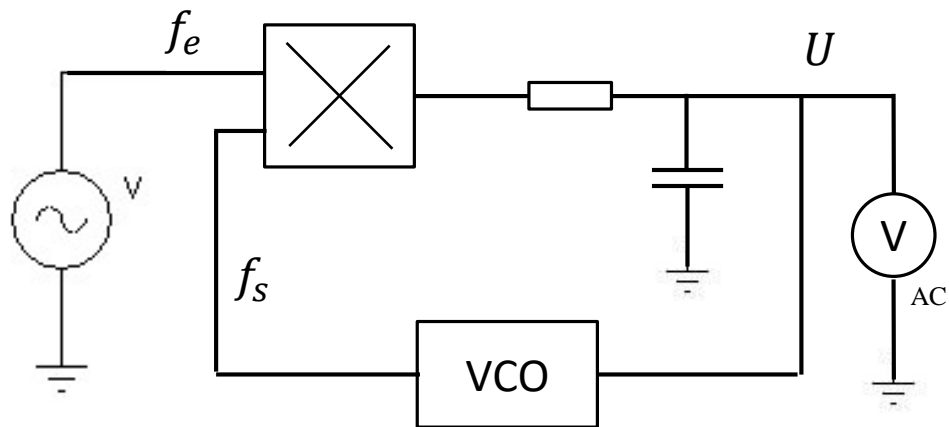
Résistance équivalente



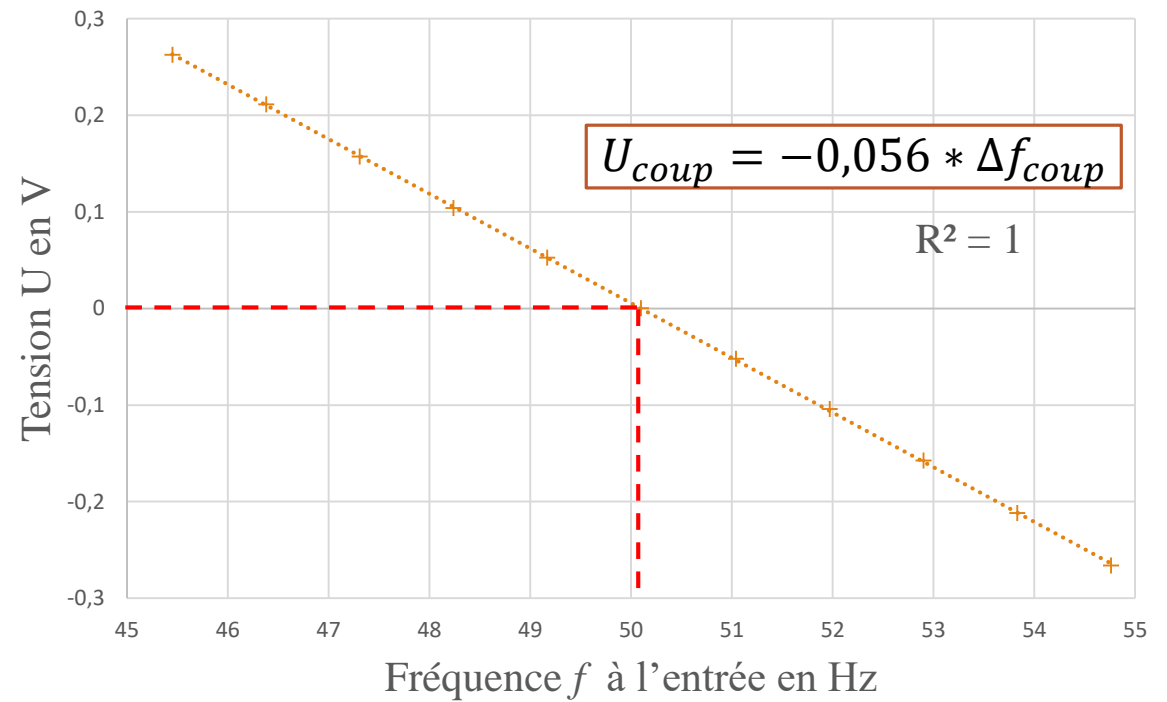
# Boucle à verrouillage de phase: Principe de fonctionnement



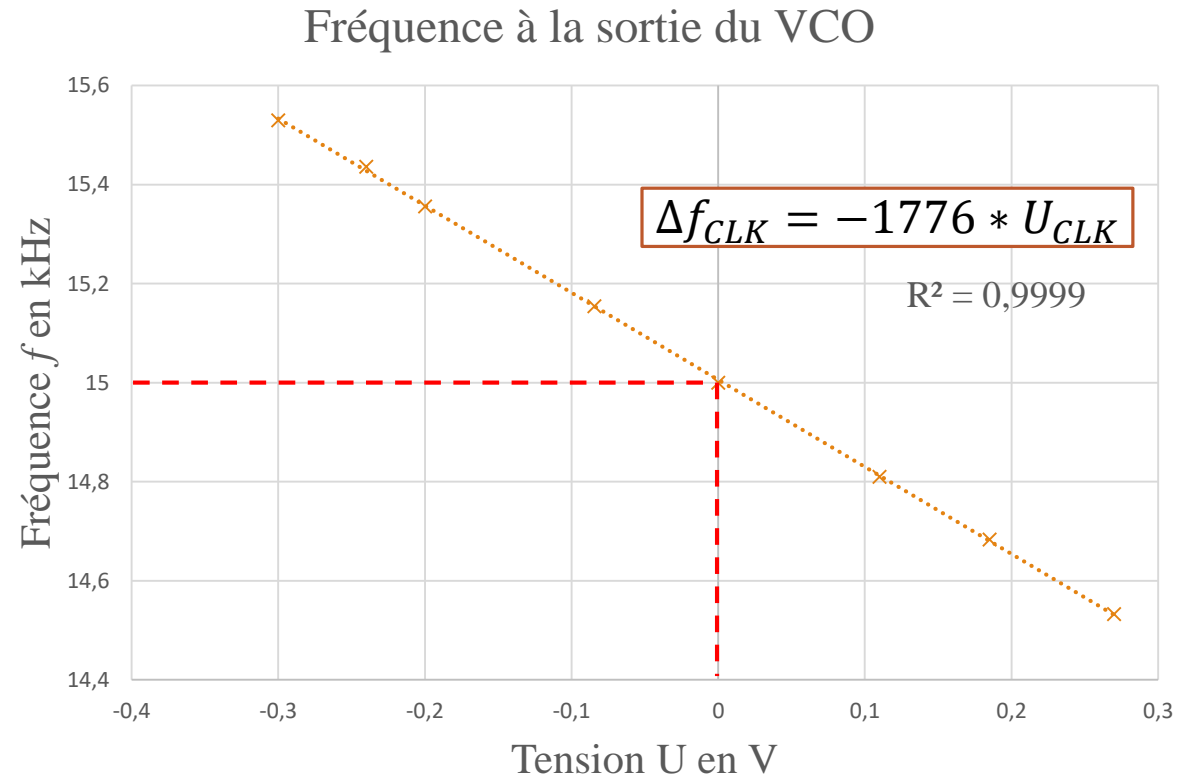
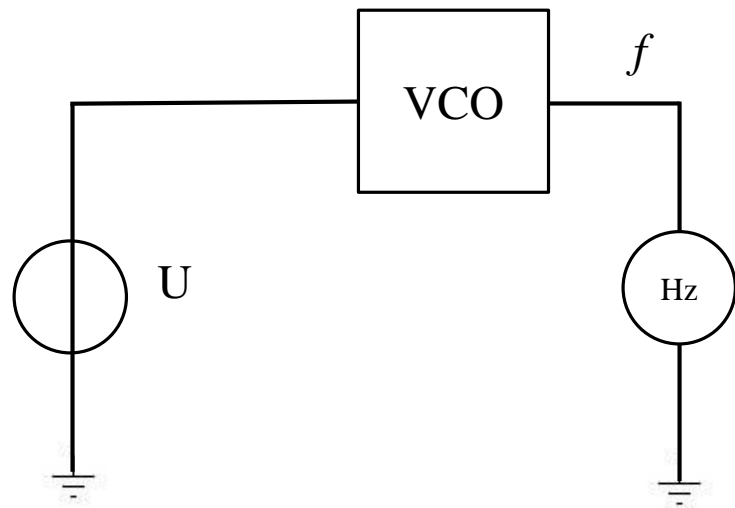
# Boucle à verrouillage de phase: Caractéristique en 50 Hz:



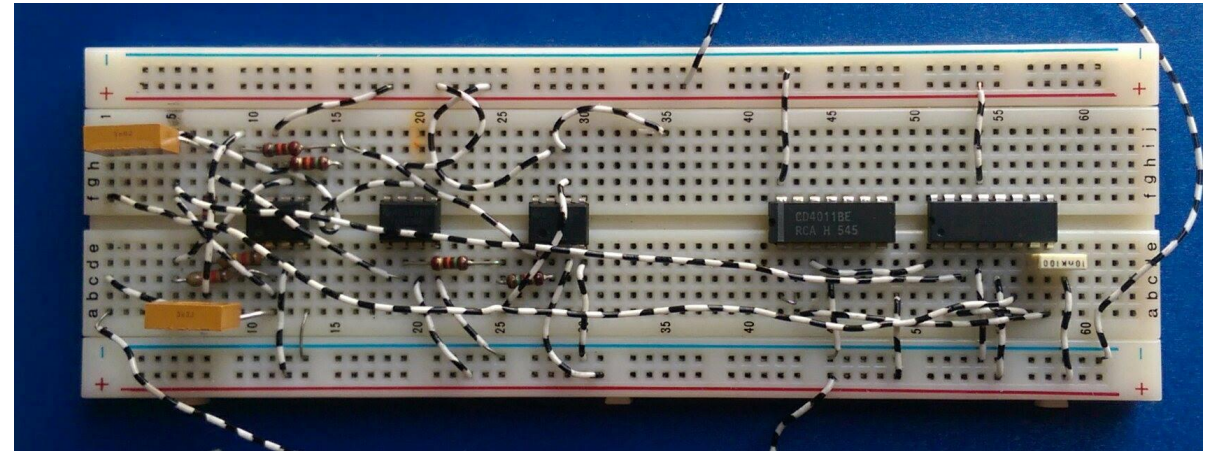
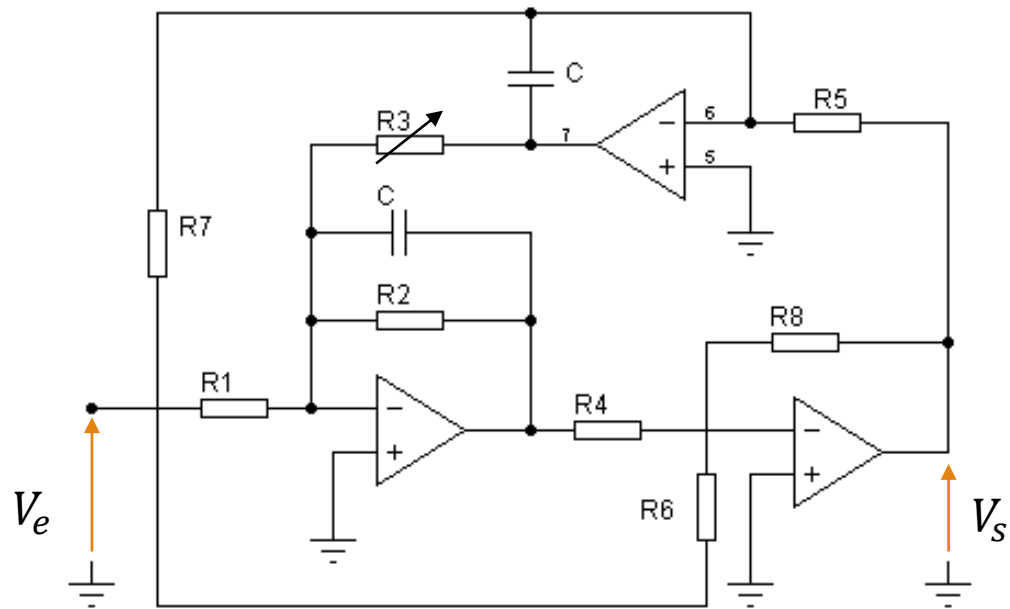
Tension à la sortie de la PLL



# Oscillateur commandé en tension: Caractéristique en 15 kHz:



## Systeme final:



## Calcul de l'amplificateur:

$$\Delta f_{coup} = -0,0017 * \Delta R_3 \quad \text{avec} \quad \Delta f_{bruit} = \Delta f_{coup}$$

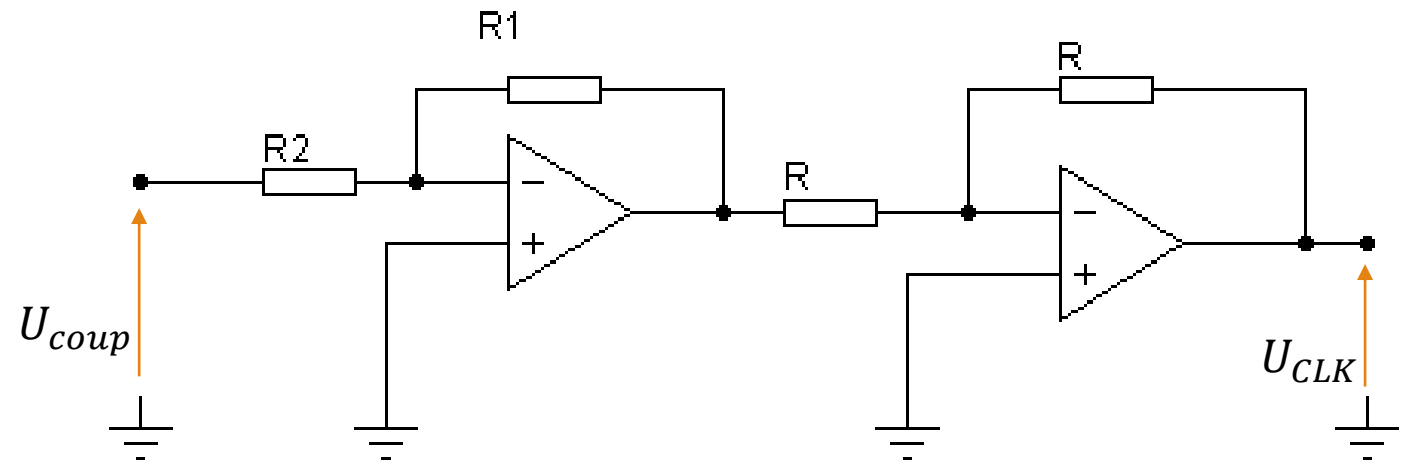
$$\Delta R_3 = -2,13 * \Delta f_{CLK}$$

$$\Delta f_{CLK} = -1776 * U_{CLK}$$

$$U_{coup} = -0,056 * \Delta f_{coup}$$

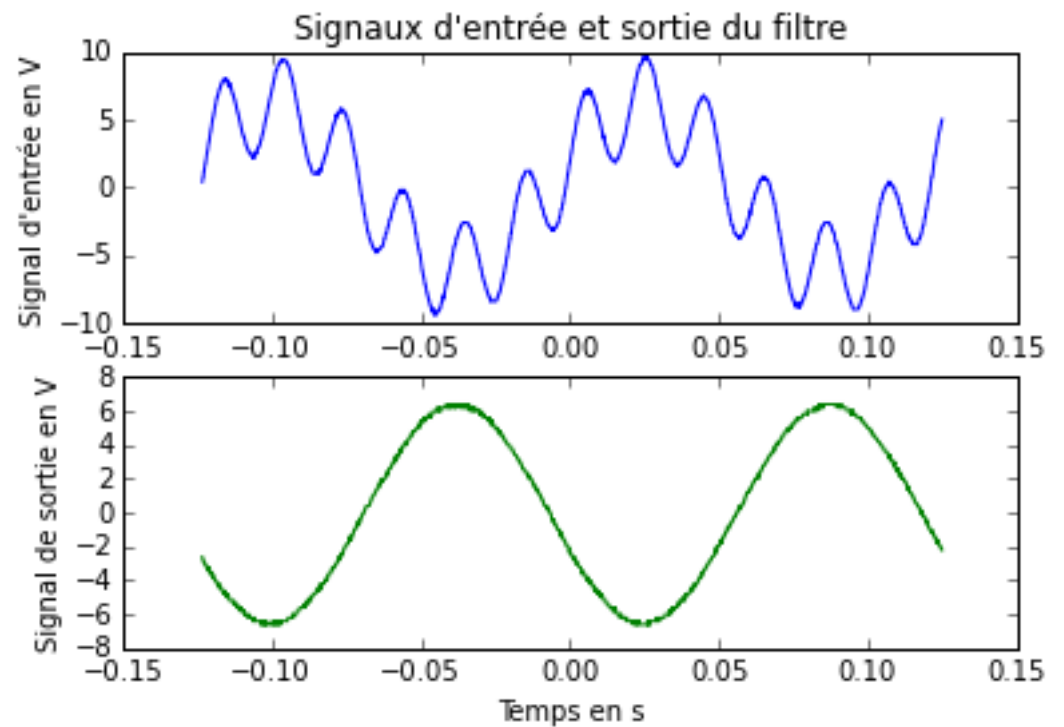
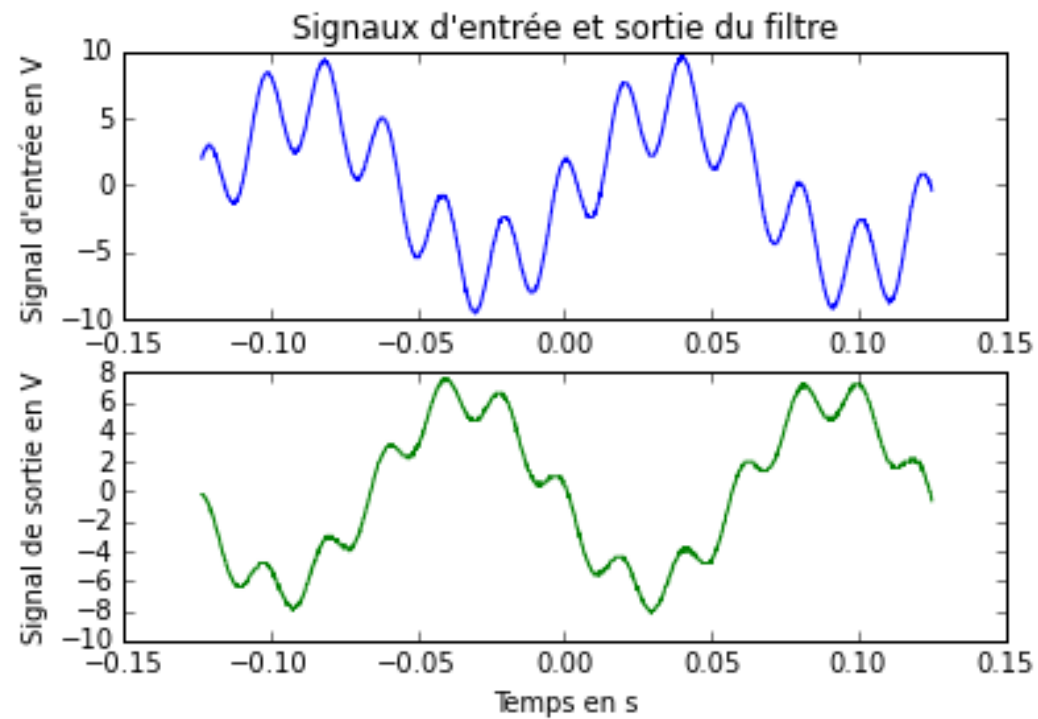
$$K = \frac{U_{CLK}}{U_{coup}} = \frac{1}{0,0036 * 0,056 * 1776}$$

$$K = 2,79$$



$$K = \frac{U_{CLK}}{U_{coup}} = \frac{R_1}{R_2}$$

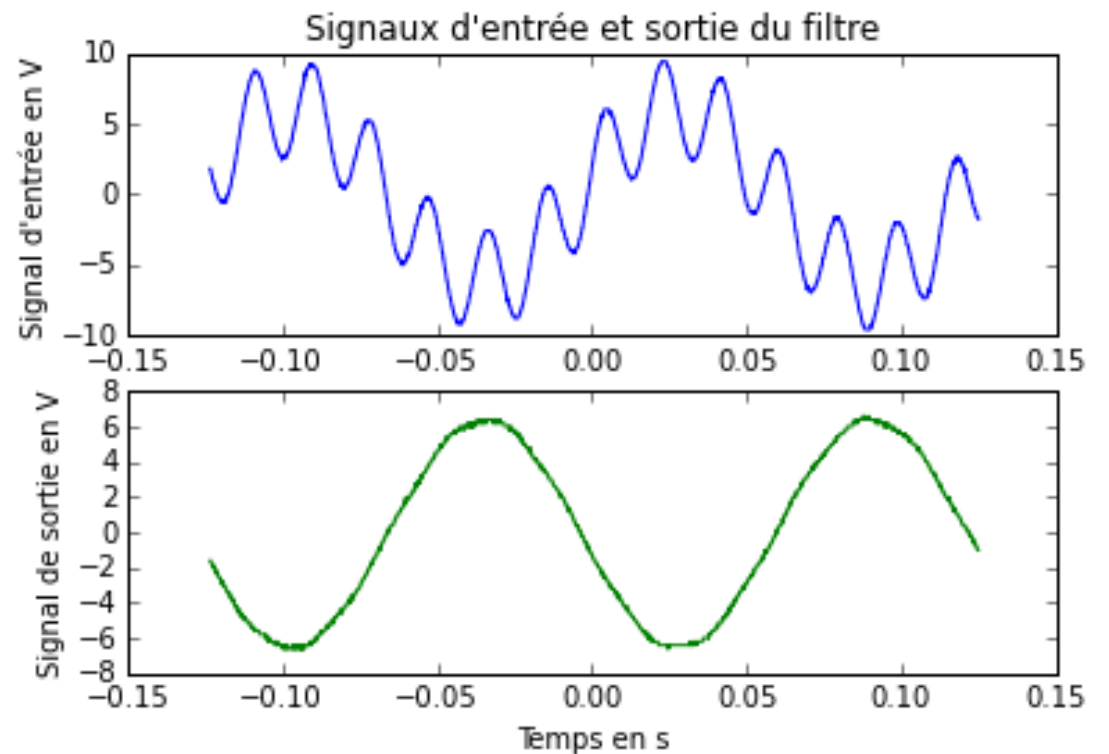
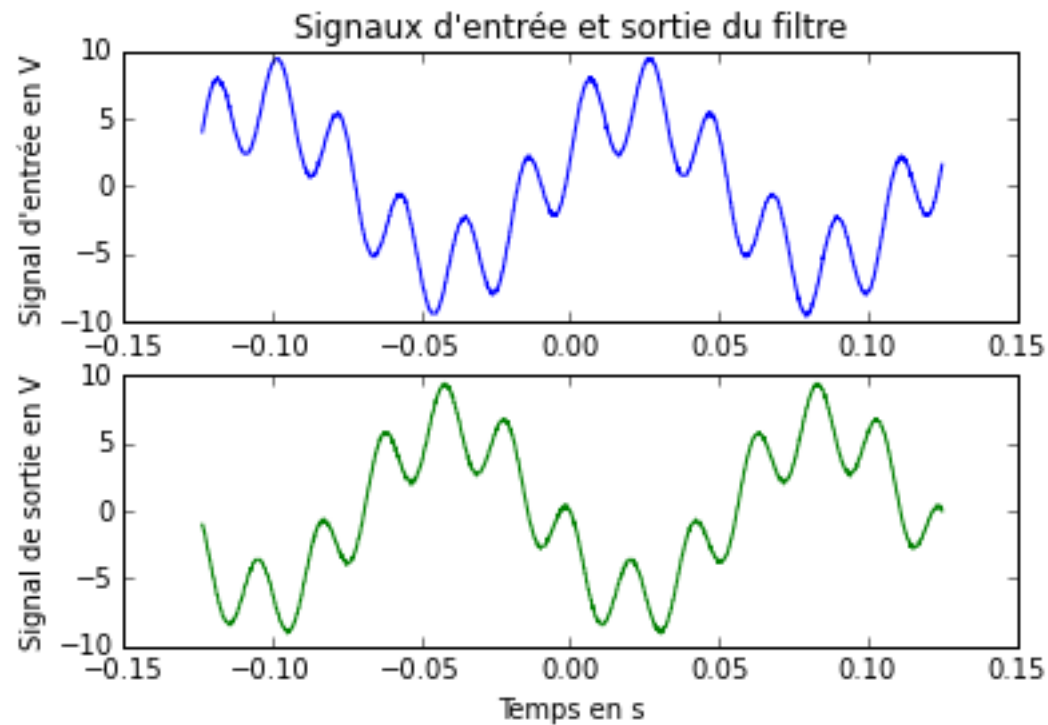
## Résultats expérimentaux:



Fréquence du bruit: 49 Hz

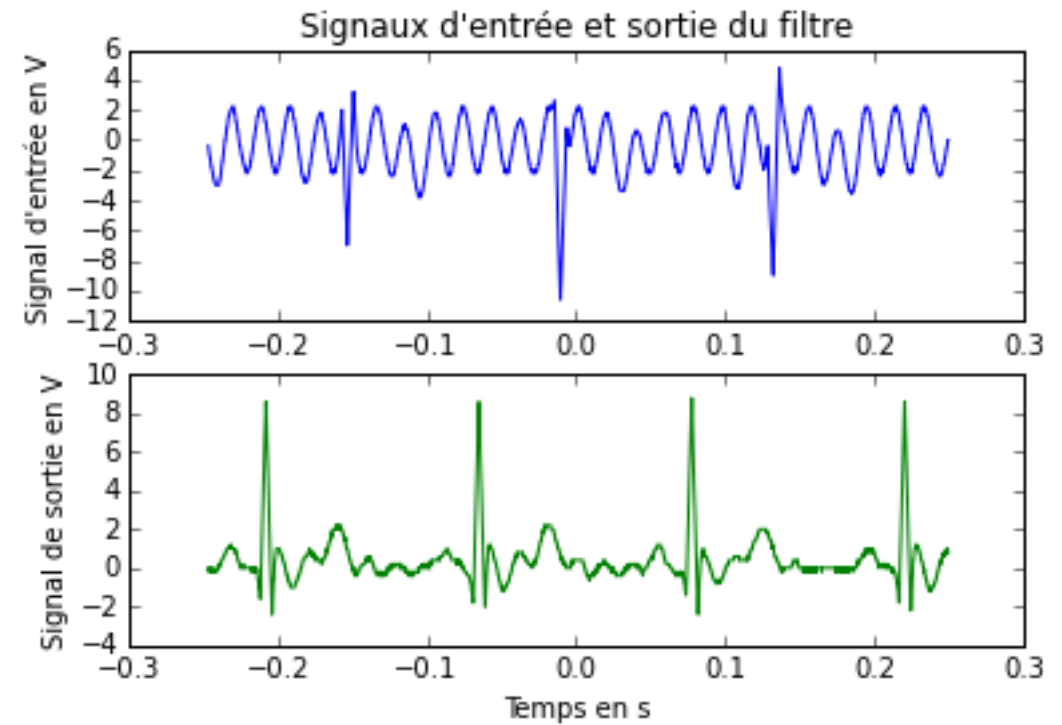
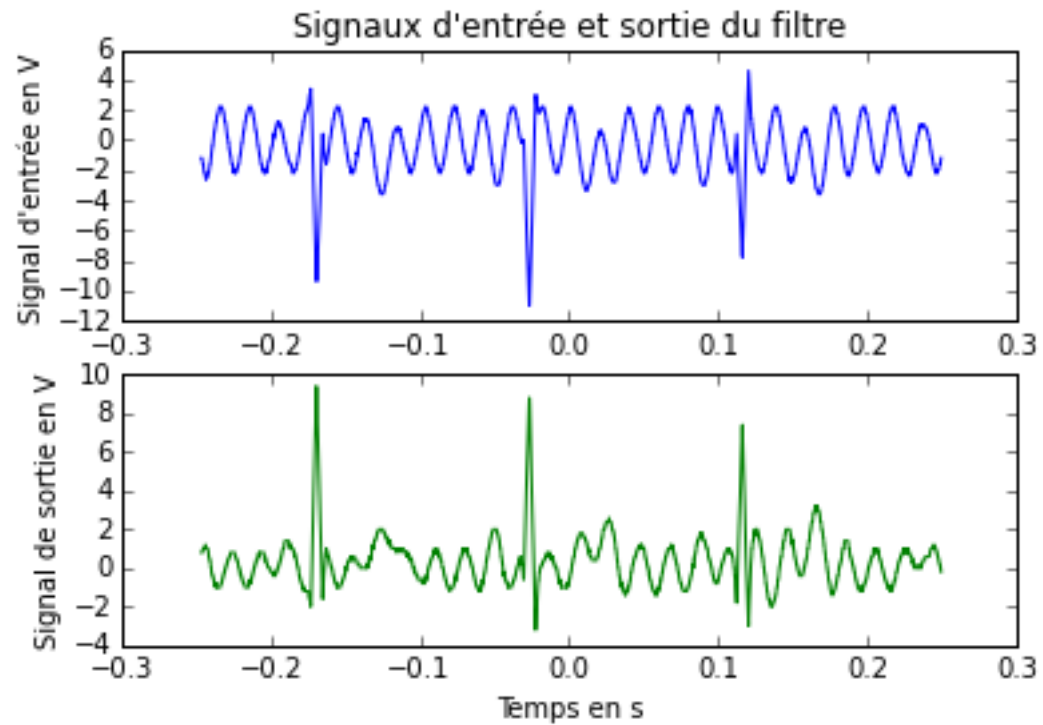


## Résultats expérimentaux:



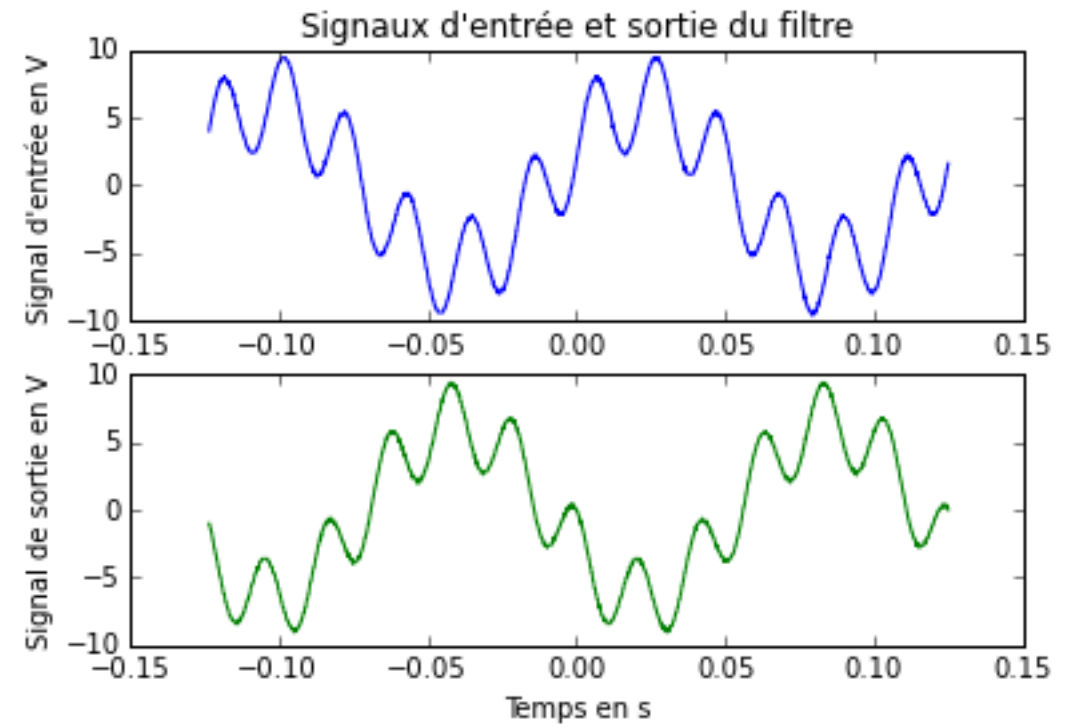
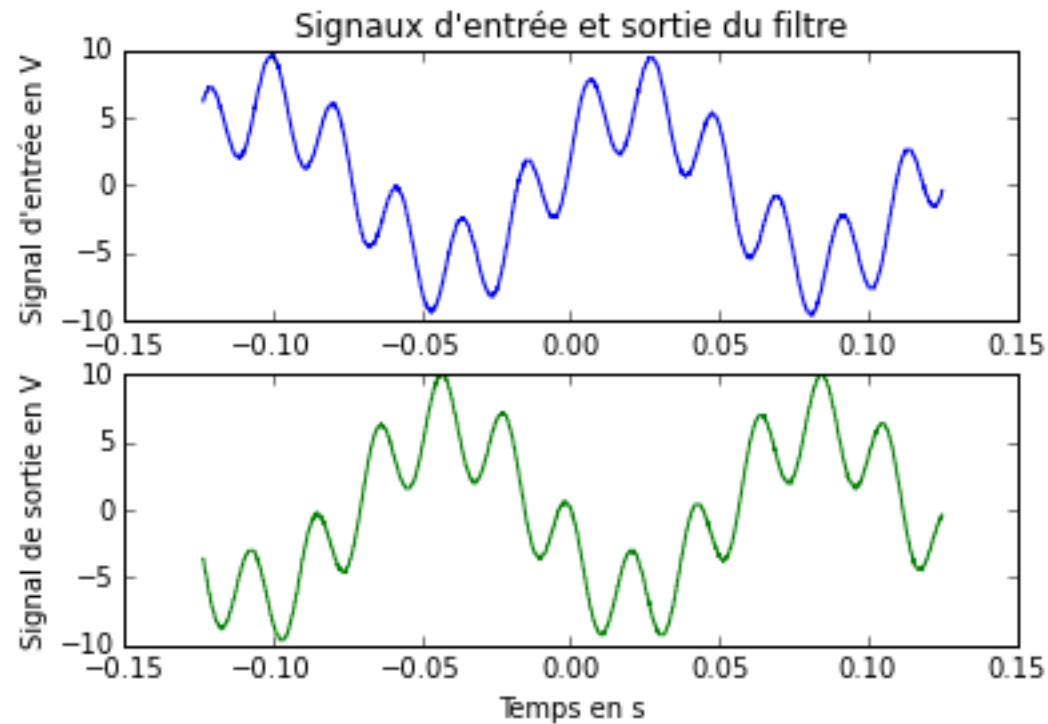
Fréquence du bruit: 53 Hz

## Résultats expérimentaux:



Fréquence du bruit: 52 Hz

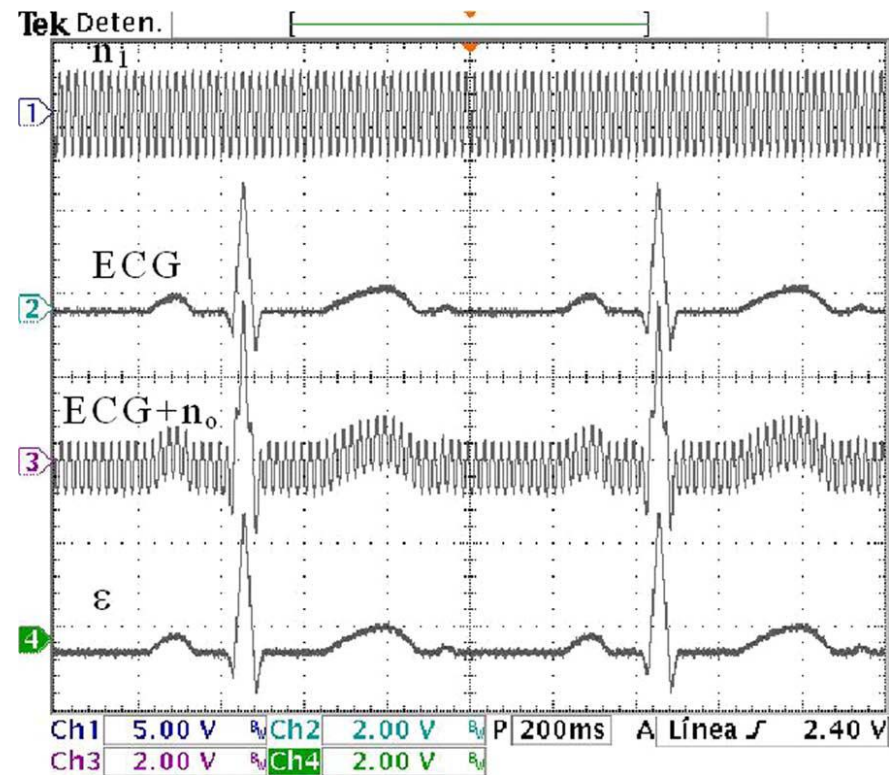
## Résultats expérimentaux:



Fréquence du bruit: 55,5 Hz

# Conclusion

- Réalisation de l'objectif
- Limites du modèle
- Contraintes retenues
- Pertinence du système



# Annexe 1

```
1 # -*- coding: utf-8 -*-
2 """
3 Created on Mon Jun  5 11:51:46 2017
4
5 @author: youss
6 """
7
8 from matplotlib.pyplot import *
9 from numpy import *
10 from pylab import *
11
12 R1=200e3
13 R2=200e3
14 #R3=153 #variable
15 R4=14.7e3
16 R5=14.7e3
17 R6=14.7e3
18 R7=14.7e3
19 R8=14.7e3
20 C=215e-9
21
22 def H1(omega):
23     R3=14.9e3
24     return ((1/R1) - R5/(R2*R6) - 1j*(R4*C/R6)*omega + 1j/(R7*R3*C*omega)) / (R4/(R2*R8) + 1j*(R4*C/R8)*omega - 1j*(1/(R3*R5*C*omega)))
25
26 def H2(omega, f):
27     R3=(75.56-f)/0.0017
28     return ((1/R1) - R5/(R2*R6) - 1j*(R4*C/R6)*omega + 1j/(R7*R3*C*omega)) / (R4/(R2*R8) + 1j*(R4*C/R8)*omega - 1j*(1/(R3*R5*C*omega)))
29
30 puissance_omega=arange(10,100,0.01)
31 omega=10*puissance_omega
32 phase=angle(H1(omega), 'deg')
33 module=20*log(absolut(H1(omega)))
34
35 subplot(211)
36 semilogx(omega,module)
37 ylabel("Gain en db")
38 grid(True)
39 plt.title('Module')
40
41 subplot(212)
42 semilogx(omega,phase)
43 xlabel("Pulsation en rad/s")
44 ylabel("Phase en rad")
45 grid(True)
46 plt.title('Phase')
47
48 show()
49
```

# Annexe 2

---

```
1# -*- coding: utf-8 -*-
2"""
3Created on Mon Jun  5 12:36:07 2017
4
5@author: youss
6"""
7
8import matplotlib.pyplot as plt
9from scipy.stats import linregress as reglin
10
11fh=open("53hz2.txt","r")
12donnees = fh.read()
13donnees=donnees.splitlines()
14x=[]
15y1=[]
16y2=[]
17
18points=[i for i in range(len(donnees))]
19for el in donnees:
20    a=el.split(",")
21    x.append(float(a[3]))
22    y1.append(float(a[4]))
23    y2.append(float(a[10]))
24
25plt.subplot(211)
26plt.plot(x,y1)
27plt.xlabel("Temps en s")
28plt.ylabel("Signal d'entrée en V")
29
30plt.title("Signaux d'entrée et sortie du filtre ")
31
32plt.subplot(212)
33plt.plot(x,y2,'g')
34plt.xlabel("Temps en s")
35plt.ylabel("Signal de sortie en V")
36
37plt.show()
38
```